

Autonomous Mobile Robots

HD Series

Autonomous Mobile Robots that self-navigate to transport payloads up to 1500 Kg

• Natural feature navigation:

Automatically plans efficient routes and prevents collisions

• Fleet management:

Operates in coordination with a fleet of up to 100 AMRs

• Easy deployment:

Installs quickly, without facility modifications



Ordering Information

| Туре | HAPS | Side Lasers | Charging Station | Pendant | Top Plate | Part Number |
|---------|--------|----------------|---------------------|---------|--------------|----------------|
| | No | No | No | No | No | 37480-00000 |
| | | Yes | INO | | | 37480-00010 |
| | | No | Yes | Yes | Yes | 37480-10004 |
| | Single | No | No | No | No | 37480-00100 |
| | | Yes | | | | 37480-00110 |
| HD-1500 | | No | Yes | Yes | Yes | 37480-10104 |
| | | Yes | | | | 37480-10114 |
| | Davida | No | No | No | No | 37480-00200 |
| | | Yes | | | | 37480-00210 |
| | Double | No | Yes | Yes | Yes | 37480-10204 |
| | | Yes | | | | 37480-10214 |

Note: To ensure proper fleet management, please contact an OMRON representative before ordering AMRs to add to an existing fleet. **Note:** The battery for the HD-1500 must be ordered separately (part number 68330-000).

Accessories and Optional Items

| Item | Details | Part Number |
|---|---|-------------|
| EM2100 | Network appliance that acts as a Fleet Manager or Fleet Simulator | 14328-200 |
| Top Plate Kit | Upper plate kit of the AMR. It is not necessary for building a customer payload structure | 68950-000 |
| Pendant | Handheld, external input device for manually driving an AMR. It is typically used for map creation | 68940-000L |
| Charging Station | Includes a Power Supply Box and Docking Target | 68910-010 |
| Power Supply Box | Supplies power to the Docking Target or battery for charging purposes | 68310-000 |
| Docking Target | A fixed object that the AMR docks to for autonomous charging. Connects to the Power Supply Box | |
| Battery Removable and rechargeable power source for the AMR | | 68330-000 |
| Side Laser Extension Cables, | 1 m length | 22115-000F |
| Communication | 2 m length | 22117-000F |
| Side Laser Extension Cables, | 1 m length | 22800-000F |
| Power | 2 m length | 22802-000F |
| Wireless Antenna Extension Kit | Two cables, 2 m each, two dipole antennas | 68955-000 |
| CAPS License | Licensed version of the Cell Alignment Positioning System | 20271-805 |

HD Series

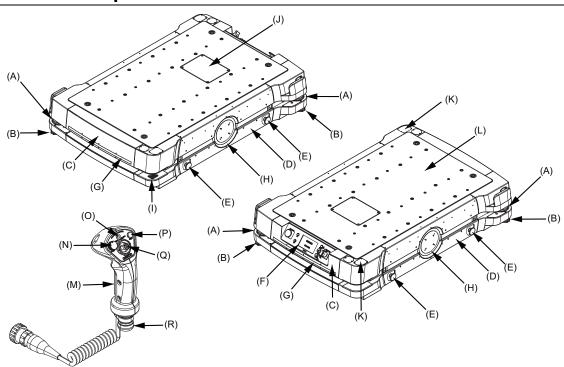
Fleet Operations Workspace Solutions

| Product Name | Configuration | Part Number |
|--|--|-------------|
| Primary Fleet Operations Workspace (FLOW) Core License, 1 Year | Entitlement for a 1 year renewable Primary FLOW Core license, runtime and development, per AMR connection | 20271-800 |
| Primary Fleet Operations Workspace (FLOW) Core License, 5 Year | Entitlement for a 5 year renewable Primary FLOW Core license, runtime and development, per AMR connection | 20271-806 |
| Secondary Fleet Operations Workspace (FLOW) Core License, 1 Year | Entitlement for a 1 year renewable Secondary FLOW Core license per fleet, redundant runtime | 20271-802 |
| Secondary Fleet Operations Workspace (FLOW) Core License, 5 Year | Entitlement for a 1 year renewable Secondary FLOW Core license per fleet, redundant runtime | 20271-807 |
| Primary Fleet Manager | EM2100 Appliance with Temporary 120 Day Fleet Operations Workspace License | 20271-900 |
| Secondary Fleet Manager | EM2100 Appliance with Temporary 120 Day Fleet Operations Workspace License | 20271-901 |
| Bundle. Fleet Simulator | EM2100 appliance with Entitlement for perpetual Fleet Simulator License | 20271-903 |
| License, Fleet Simulator | Entitlement for perpetual Fleet Simulator license for use with existing EM2100 appliance, simulation runtime and development | 20271-804 |
| License, Fleet Operations Workspace iQ | Entitlement for a 1 year renewable FLOW iQ license | 20271-701 |
| License, Fleet Operations Workspace IQ | Entitlement for a 5 year renewable FLOW iQ license | 20271-705 |

- * To obtain the latest version of the Fleet Operations Workspace (FLOW) Core software, contact your local OMRON representative. Please note that an active subscription is required for access to software upgrades.

 * Expiration of a 1 year subscription license without renewal will result in cessation of the fleet management functions of the OMRON AMR solution
- until the license is renewed.
- * After four consecutive 1 year renewals (for a total of 5 years) or after purchase of a 5 year license, all fleet management functions will continue to operate without requiring subsequent subscription renewals. Please note that an active subscription will still be required to have access to subsequent software releases, including bug fixes, feature upgrades and performance improvements.

Features and Components



| Item | Description | Item | Description |
|------|-----------------------------|------|--|
| Α | Safety Laser Scanner | J | User Access Panel |
| В | Low Laser | K | Wireless Antennas |
| С | Front / Rear Skin | L | Payload Mounting Surface (Top Plate shown) |
| D | Side Skin | М | Three-position Enabling Switch |
| Е | E-STOP Button ^{*1} | N | Speed Control |
| F | Operator Panel | 0 | Power Indicator LED |
| G | Light Strip | Р | Goal Button |
| Н | Light Disc | Q | Directional Control Stick |
| I | Charging Contacts | R | E-STOP Button |

^{*1:} Additional E-STOP buttons are provided on the Operator Panel and the Pendant.

Specifications

HD-1500

| | Item | Details | | |
|-----------------------|---|--|--|--|
| Weight (with Battery) | | 506.5 kg | | |
| | Ambient temperature | 5 to 40°C | | |
| | Storage temperature | -20 to 60°C | | |
| | Ambient humidity | 5 to 95% (non-condensing) | | |
| Environment | Operating environment | Indoor usage only, no excessive dust, no corrosive gas | | |
| | Altitude | 2000 m maximum | | |
| | Ingress Protection Class | IP20 | | |
| | Floor requirements | No water, no oil, no dirt | | |
| | Minimum floor flatness | F _F 25 (ACI 117 standard) | | |
| Floor | Traversable step | 10 mm max. | | |
| Conditions | Traversable gap | 20 mm max. | | |
| | Climb grade | Max. 3° incline (5° with FLOW 3.0 or later) | | |
| | | Autonomous routing by localizing with safety scanning laser, based on | | |
| | Routing | environment mapping | | |
| Navigation | | Scan by driving the AMR through the environment, and upload the scan data to | | |
| | Environmental map-making method | the MobilePlanner | | |
| Payload Rating | | 1500 kg | | |
| | Run Time*1 | 12.5 h (no payload), 9 h (full payload) | | |
| | Maximum speed | 1800 mm/s | | |
| | Maximum rotation speed | 60 °/s | | |
| | Swing radius | 982 mm | | |
| | Turn radius | 0 mm | | |
| | Maximum translational acceleration | 900 mm/s ² | | |
| | Maximum rotational | 1-0-1/0 | | |
| NA - In 1994 | acceleration/deceleration | 150 °/s² | | |
| Mobility | Maximum moment of inertia | 490 kg-ms ² | | |
| | | To a position: ±50 mm | | |
| | Stop position repeatability (single AMR) | To standard target: ±25 mm, ±2° | | |
| | Cop position repositionity (entigre / time t) | With CAPS: ±8 mm, ±0.5° | | |
| | | With HAPS: ±8 mm, ±0.4° | | |
| | | To a position: ±70 mm To standard target: ±35 mm, ±2° | | |
| | Stop position repeatability (Fleet) | With CAPS: ±16 mm. ±0.5° | | |
| | | With HAPS: ±10 mm, ±0.75° | | |
| Drive wheels | Materials | Non-marking, static dissipative polyurethane on steel rim | | |
| Passive casters | Materials | Non-marking polyurethane on cast iron rim. | | |
| A ''' D | Unregulated | 48 to 56 VDC | | |
| Auxiliary Power | Regulated | 23.0 to 25.2 VDC | | |
| | Harmonized standard | EN ISO 12100, EN ISO 13849-1, EN 60204-1 | | |
| Standard | Relevant standard | ISO 10218, UL1564, UL2271, UL1740 | | |
| | Wireless | IEEE 802.11 a/b/g/n/ac | | |
| | Wireless | Two integrated wireless antennas | | |
| | | Two RJ-45 ports included for maintenance and | | |
| | Ethernet port | access to the internally mounted NX102 unit. | | |
| Signal | District I/O | Eight PNP (sourcing) inputs | | |
| Interfaces | Digital I/O | Eight PNP (sourcing) outputs | | |
| | Analog I/O | Four -10 to +10 VDC analog inputs | | |
| | - | Four -10 to +10 VDC analog outputs | | |
| | Audio | Digital audio out | | |

HD Series

| Item | | Details |
|-----------------|---------------------------|--|
| | Safety Scanning Lasers | Two Safety Scanning Lasers are included to provide a 360° detection area around the AMR. The scanning plane is positioned 175 mm above the floor. Lasers are rated as Class 1, eye-safe, PLd Safety per ISO 13849-1. |
| | E-STOP Buttons | Five E-STOP buttons are located on the AMR (sides and Operator Panel). Additional E-STOP buttons can be added to the payload structure. |
| | Low Lasers | Two Low Lasers are provided to detect objects near the floor. |
| Safety Features | Side Lasers (optional) | Two lasers, factory-mounted above safety scanning lasers, user-relocatable to the payload structure if needed. |
| , | Visual Indicators | Light discs are located on the sides of the AMR. Light strips are located on the front and back of the AMR. Additional indicators can be added. |
| | Audible Indicators | Two speakers are included. Additional buzzers can be added. |
| | Emergency Stop Interface | Dual channel emergency stop inputs and outputs. |
| | Safety Outputs | Dual channel safety outputs. |
| | Protective Stop Interface | Dual channel protective stop inputs. |
| | Display | 7-inch diagonal LCD. |
| Operator Panel | Controls | E-STOP button ON/OFF buttons Brake release button Pendant port Maintenance port Main disconnect switch |

^{*1.} Auxiliary power draw will impact these times

| MobilePlanner Software | | | |
|----------------------------------|---------------------|--|--|
| | Operating System | Windows 10 (32-bit/64-bit version) | |
| | CPU | 1.5 GHz dual-core CPU recommended | |
| MobilePlanner, | Main Memory | 1.5 GB min. (4 GB min. recommended) | |
| PC | Hard Disk | At least 200 MB of available space | |
| | Video Memory | 256 MB min. | |
| | Display | XGA 1024 × 768, 16 million colors minimum | |
| MobilePlanner, Tablet Edition | Operating System | Android OS, Version 9 or newer, minimum 2 GB of RAM | |
| Tablet Edition | System | iOS, Version 10 or newer | |
| Supported Languages | | English, German, Japanese, French, Italian, Korean, Spanish, Simplified Chinese and Traditional Chinese. | |

| EM2100 | App | oliance |
|--------|-----|---------|
|--------|-----|---------|

| Weight |
|--|
| Mounting method |
| Power Supply |
| Power Consumption |
| Operating Temperature |
| Storage Temperature |
| Operating Humidity |
| Storage Humidity |
| Ingress Protection Class |
| Main Memory |
| Storage |
| Archive Storage |
| Communication port |
| Status Display |
| Power Supply Power Consumption Operating Temperature Storage Temperature Operating Humidity Storage Humidity Ingress Protection Class Main Memory Storage Archive Storage Communication port |

Charging Station

| Maximum Current | Input current: 25 A Output current: 120 A (nominal)*1 | | |
|----------------------------------|--|--|--|
| Input Voltage | 3-phase 200 to 240 VAC, 50/60 Hz (Delta/Wye) 380 to 415 VAC, 50/60 Hz (Wye only) | | |
| Output voltage | 40 to 57 VDC | | |
| Power Consumption | 7.75 kW | | |
| Maximum Power Output | 6.84 kW | | |
| Humidity | 5 to 95%, non-condensing | | |
| Ambient Operating Temperature | 5 to 40°C | | |
| Storage Temperature | -20 to 60°C | | |
| Ingress Protection Class | IP20 (IP10 for charging pads) | | |
| Weight | Power Supply Box: 108 kg Docking Target: 27.5 kg | | |
| Docking Target Mounting | To floor and/or wall | | |
| | | | |

^{*1} Fused at 150 A

High Accuracy Positioning System

| Ingress Protection | | IP64 |
|--|----------------------|---|
| Environment | | -40 to 85°C |
| Mannatia Tana | Width | 25 mm |
| Magnetic Tape | Orientation | South up |
| | Width | 25 mm |
| Markers | Length | 300 mm min. for 500 mm/s drive speed |
| (Magnetic Tape) | Orientation | North up |
| | Separation from tape | 20 to 30 mm |
| Protective covering tape (recommended) | | Mighty Line Safety Floor Tape, Solid (102 mm width) |
| Stop Position | Single AMR | ±8 mm position, ±0.4° rotation |
| Repeatability | Fleet | ± 10 mm position, $\pm 0.75^{\circ}$ rotation |

Cell Alignment Positioning System (CAPS)

| Stop Position Repeatability - Single AMR | ±8 mm position, ±0.5° rotation |
|---|---------------------------------|
| Stop Position Repeatability - Fleet | ±16 mm position, ±0.5° rotation |
| Туре | Software license |

Pendant

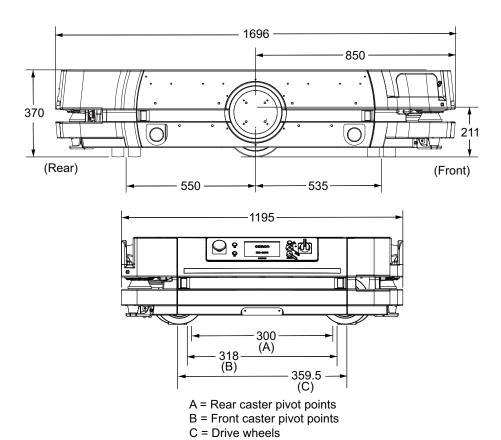
| Ambient Operating Temperature | 0 to 40°C |
|----------------------------------|--------------------------|
| Storage Temperature | -20 to 65°C |
| Humidity | 5 to 95%, non-condensing |
| Altitude | 2000 m |
| Ingress Protection Class | IP30 |

Battery

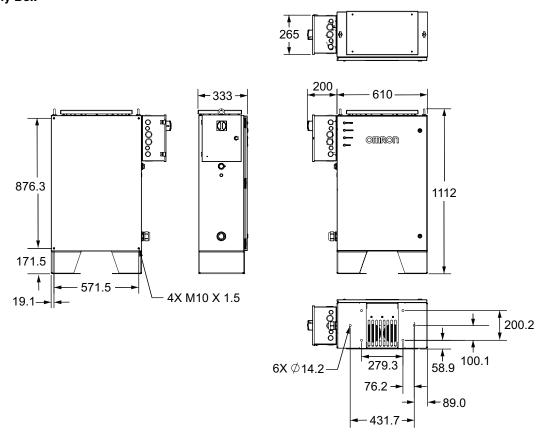
| Voltage | 48 to 56 VDC (52.8 nominal) | |
|----------------------------------|--|--|
| | , , | |
| Capacity | 70 Ah nominal | |
| Recharge Time | 40 min (from empty to full) | |
| Charge Cycles | 9000 recharge cycles (battery cell nominal) | |
| Charging Method | Automatic or manual | |
| Ambient Operating Temperature | 5 to 40°C | |
| Storage Temperature | -20 to 60°C (less than 2 weeks) -20 to 35°C (more than 2 weeks) | |
| Humidity | 5 to 95%, non-condensing | |
| Altitude | 4500 m, operating 15240 m, transporting | |
| Ingress Protection Class | IP20 | |
| Weight | 69.5 kg | |

Dimensions (Unit: mm)

HD-1500 AMR

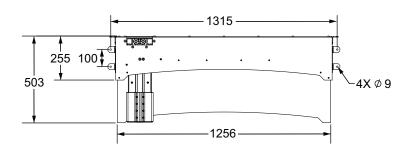


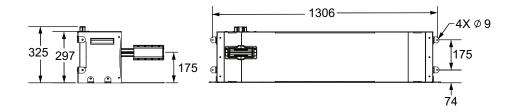
Power Supply Box



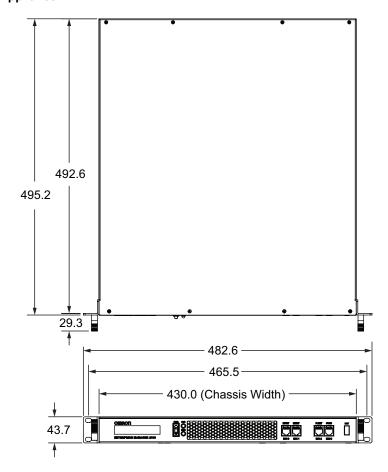
Dimensions (Unit: mm)

Docking Target





Fleet Manager EM2100 Appliance



HD Series

Related Manuals

| Manual No. | Title |
|------------|--|
| l614 | Mobile Robot Software Suite User's Guide |
| l617 | Advanced Robotics Command Language Reference Manual |
| l618 | Advanced Robotics Command Language Enterprise Manager Integration Manual |
| I634 | EM2100 Installation Manual |
| I635 | Fleet Operations Workspace Core User's Manual |
| 1636 | Fleet Operations Workspace Core Migration Manual |
| I637 | Fleet Operation Workspace Core Integration Toolkit User Manual |
| 1649 | Fleet Simulator User's Manual |
| l645 | HD-1500 Platform User's Manual |
| 1647 | Mobile Robot HD Safety Manual |

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